## Digital switch setting type, temperature controller

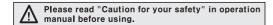
### ■ Features

•Various size by DIN specification

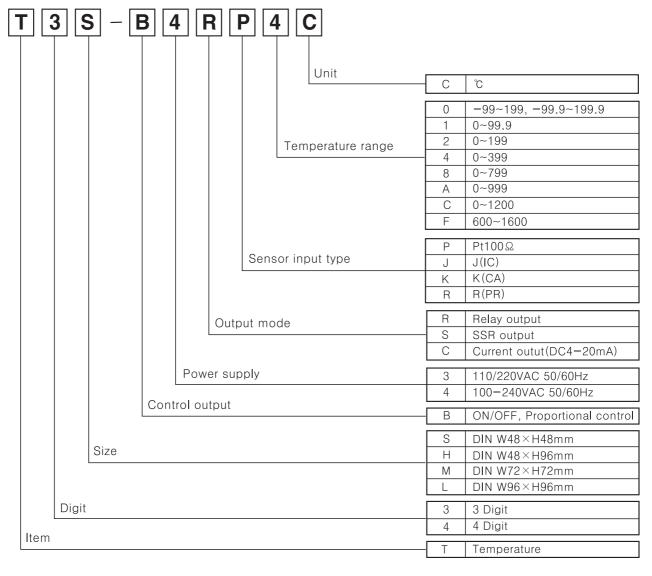
•Accuracy: F • S  $\pm 0.5\%$ 

•Universal power: T3S Series





### Ordering information



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# **Digital Switch Setting Type**

## **■**Temperature range for each sensor

Model		T3S			ТЗН				T4M / T4L			
Sensor input type		Thermocouples		RTD	Thermocouples		RTD	Thermocouples		oles	RTD	
		J(IC)	K(CA)	Pt100Ω	J(IC)	K(CA)		Pt100Ω	J(IC)	K(CA)	R(PR)	Pt100Ω
	1600										1600℃	
	1200				]]				L	120	0℃	
	1000						99℃					
	1000		799℃		1	399℃				799℃		
01 1 1	800				1				ii			1
Standard	600	399℃	399℃	399℃	399℃	399℃		399℃	399℃	399℃	000℃	399℃
scale range	400	199℃ ■		199℃				199℃ ■				199.9℃ ■
	200			99.9℃ ■				99.9℃ ■				
	100											· · · · · · · · · · · · · · · · · · ·
	0											
-	-100				<del>  </del>				<b> </b>			-99.9℃

\*In case, the sensor is R(PR) type, it is not available to indicate the temperature and control correctly.

### Specifications

Model		T3S	ТЗН	T4M	T4L					
Power supply		100-240VAC 50/60Hz 110/220VAC 50/60Hz								
Allowable voltage		90~110% of power supply								
range										
Power consumption		5VA 3VA								
Display method		7 Segment LED Display								
Character size		W4×H8mm	W6×H10mm	W7.2×H9.8mm	W9.5×H14.2mm					
Display accuracy		$F \cdot S \pm 1\% \text{ rdg } \pm 1 \text{digit}$ $F \cdot S \pm 0.5\% \text{ rdg } \pm 1 \text{digit}$								
Setting type		Digital switch setting								
Setting accuracy		$F \cdot S \pm 1\%$ $F \cdot S \pm 0.5\%$								
Sensor input		Thermocouples: K(CA), J(IC), R(PR) / RTD: Pt100Ω [There is no R(PR) in T3S, T3H series]								
<u> </u>	e resistance	Thermocouples: Max. 100Ω / RTD: Max. 5Ω per a wire								
Control	ON/OFF Control	Hysteresis: F•S 0.5% ±0.2% Fixed	Hysteresis∶F•S 0.2~3%							
	Proportional Control	Proportional band: F•S ±3% fixed, Period: 20sec. fixed□	Proportional band ∶F•S 1~10% variable, Period∶20sec. fixed□							
Reset VR range		F•S ±3% variable								
Control output		<ul> <li>Relay output:</li> <li>250VAC 2A 1c</li> <li>SSR output:</li> <li>12VDC ±3V 20mA max.</li> <li>Current output:</li> <li>4-20mADC Load</li> <li>600 Ω max.</li> <li>Relay output: 250VAC 3A 1c</li> <li>SSR output: 12VDC ±3V 20mA max.</li> <li>Current output: 4-20mADC Load 600 Ω max.</li> </ul>								
Self-diagnosis		Built—in burn out function								
Insulation resistance		Min. 100MΩ (at 500VDC)								
Dielectri	c strength	2000VAC 50/60Hz for 1 minute								
Noise strength		±1kV the square wave noise(pulse width:1µs) by the noise simulator								
Vibration	Mechanical	0.75mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 1 hour								
	Malfunction	•	0.5mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 10 minutes							
Shock	Mechanical	300m/s² (Approx. 30G) 3 times at X, Y, Z direction								
	Malfunction	100m/s² (Approx. 10G) 3 times at X, Y, Z direction								
Relay	Mechanical	Min. 10,000,000 times								
life cycle	Electrical	Min. 100,000 times(250VAC 3A at resistive load)								
Ambient temperature		-10 ~ +50℃ (at non-freezing status)								
Storage temperature		-20 ~ +60℃ (at non-freezing status) □								
Ambient humidity		35~85%RH								
Unit weig	ght	Approx. 196g	Approx. 496g	Approx. 399g	Approx. 468g					

**<sup>\*</sup>**F.S is same with sensor measuring temperature range.

(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/ Speed/ Pulse meter

(G) Display unit

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

(P) Production stoppage models & replacement

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Ex) In case of measurement temperature range is from -99.9  $\sim$  199.9 °C, Full scale is 299.8.

### Connections

\*\*RTD(Resistance temperature detector) : Pt  $100\Omega(3-\text{wire type})$  \*\*Thermocouple : K, J, R

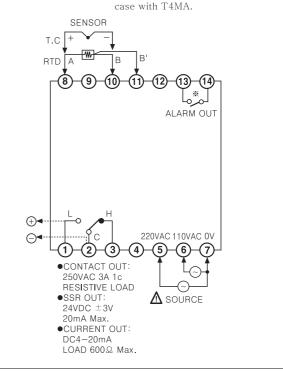
▲ SOURCE 100-240VAC

50/60Hz 5VA

### •T3S ●CONTACT OUT: 250VAC 2A 1c RESISTIVE LOAD •SSR OUT : 12VDC $\pm$ 3V 20mA Max. •CURRENT OUT DC4-20mA LOAD 600Ω Max. + (5) (4) В 6 В 7 SENSOR ≱

RTD

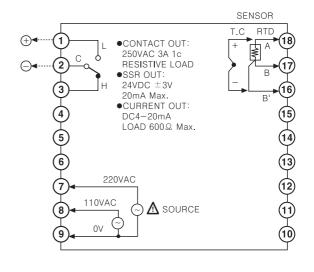
● **T4M**\*\* Although T4M has an alarm terminal, it does not work since it uses the same



#### ●T3H

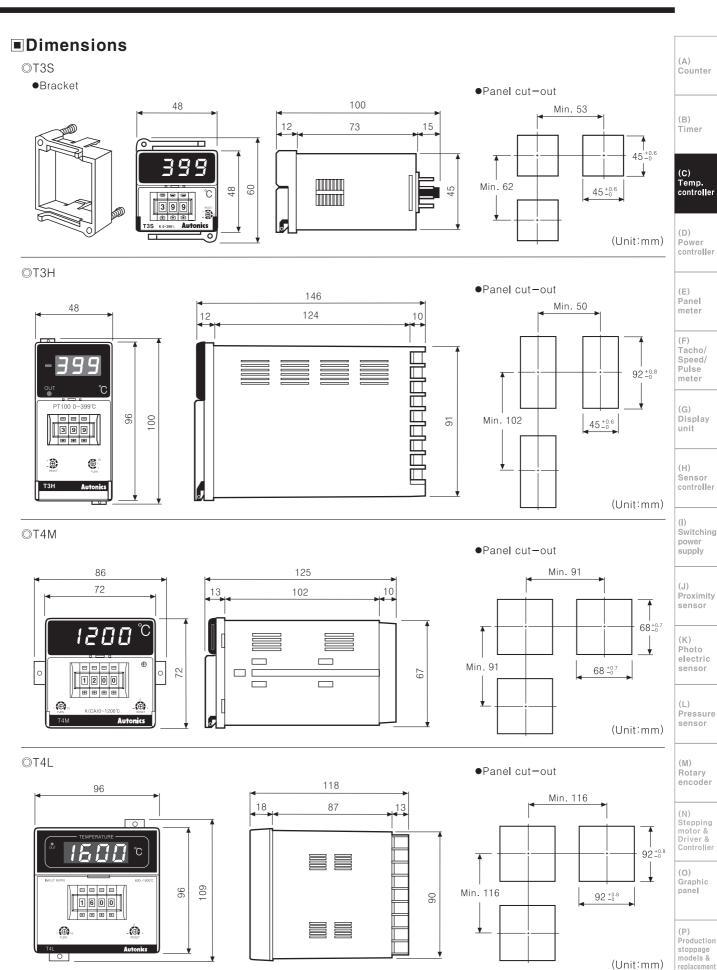
### •CURRENT OUT: 0V DC4-20mA LOAD 600Ω Max. 110VAC ----▶⊕ 220VAC **.**►⊝ **⚠** SOURCE •CONTACT OUT: 250VAC 3A 1c RESISTIVE LOAD ●SSR OUT: 24VDC ±3V 20mA Max. **+** RTD T.C SENSOR

### ●T4L



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# **Digital Switch Setting Type**

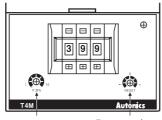


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## T3S/T3H/T4M/T4L

### ■ Proper usage

### OUsing front volume



P.B volume

Reset volume

- ●P.B volume: In case of ON/OFF control, set variable F.S 0.2~3% of hysteresis and in case of proportional control, set variable F.S 1~10% of hysteresis. However, hysteresis (F.S 0.5%) and proportional band (F.S 3%) are fixed in T3S.
- •Reset volume: Adjusting the offset generated by using proportional control. Adjusting range of reset volume is F.S ±3%. Do not change the reset volume when using ON/OFF control.



- ①Turn left when offset value is higher than setting value. (Direction ①)
- ②Turn right when offset value is lower than setting value. (Direction ②)

#### ○Normal/Reverse operation

Reverse operation executes to output ON when process value is lower than setting value and it is used for heating. Normal operation runs conversely and is executed for cooling. (This item runs as a reverse operation)

# OHow to select ON/OFF or proportional by plug pin

Factory specification is proportional control.

When using ON/OFF control, transfer the switch of control mode from P to F after detaching the case from its body. When control output is current output, P control is fixed, there is no switch Pin of control mode.

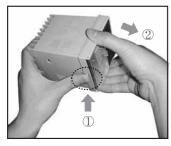


P F ON/OFF control

Proportional control

#### Case detachment

●T4L/T3H

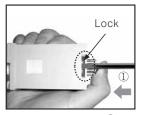


Pressing the front guide of Lock toward ① and squeeze and pull toward ②, it is detached.

#### ●T4L/T3H



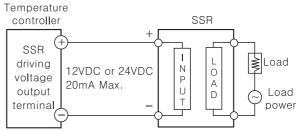
Open the front guide, turn it toward ① and pull toward ②, it is detached.



Pressing pin plug ①, raise it up with a driver as ② and it is detached.

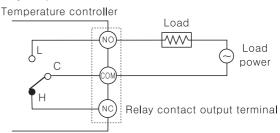
## Application of temperature controller and load connection

•SSR output connection

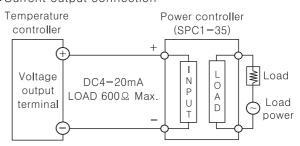


- \*When using voltage(for driving SSR) in the other purposes, do not over the range of thd rating current.
- \*\*Please aware that each series has different voltage (for driving SSR).

#### Relay output connection



- \*Be aware that each model has different contact capacity of RY. When load capacity is high, please use sub relay, which has high contact capacity.
- Current output connection



\*The current value of 4-20mADC is available at lower than  $600\Omega$  of resistive load.

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