

Incremental ø 40mm Shaft/Hollow Shaft/Built-in Type

Diameter ø 40mm Shaft type/Hollow type/Built-in type Incremental Rotary encoder

■ Features

- Easy installation at narrow space
- Small rotor inertia
- Wide range of power supply :
5VDC, 12-24VDC ±5%
- Various output types

⚠ Please read "Caution for your safety" in operation manual before using.



■ Ordering information

Series	Shaft type	Hollow type	Pulse/1 Revolution	Output phase	Output	Power supply	Cable
S: Shaft type H: Hollow type HB: Hollow built-in type	External 6: ø 6mm 8: ø 8mm	Inner 6: ø 6mm 8: ø 8mm 10: ø 10mm 12: ø 12mm	Refer to resolution	2: A, B 3: A, B, Z 4: A, $\bar{A}$, B, $\bar{B}$ 6: A, A, B, $\bar{B}$, Z, $\bar{Z}$	T: Totem pole output N: NPN open collector output 3: Voltage output L: Line driver output(*)	5 : 5VDC ±5% 24: 12-24VDC ±5%	No mark: Normal type (*) 2C: Cable outgoing connector type

*Standard : E40S6-**PULSE**-3-N-24
E40H8-**PULSE**-3-N-24
E40HB8-**PULSE**-3-N-24

*Standard: A, B, Z *The power of Line driver is only for 5VDC

*Cable length : 250mm

■ Specifications

Item		Diameter ø 40mm shaft type of Incremental rotary encoder	
Resolution(P/R)		(Note1) *1, *2, *5, 10, *12, 15, 20, 23, 25, 30, 35, 40, 45, 50, 60, 75, 100, 120, 150, 192, 200, 240, 250, 256, 300, 360, 400, 500, 512, 600, 800, 1000, 1024, 1200, 1500, 1800, 2000, 2048, 2500, 3000, 3600, 5000 (Not indicated type is available to customize)	
Electrical specification	Output phase	A, B, Z phase (Line driver : A, $\bar{A}$, B, $\bar{B}$, Z, $\bar{Z}$ phase)	
	Phase difference of output	Phase difference between A and B : $\frac{T}{4} \pm \frac{T}{8}$ (T=1 cycle of A phase)	
	Control output	Totem pole output	• Low $\Rightarrow$ Load current: Max. 30mA, Residual voltage : Max. 0.4VDC • High $\Rightarrow$ Load current: Max. 10mA, Output voltage (Power supply 5VDC): Min. (Power supply-2.0)VDC, Output voltage (Power supply 12-24VDC): Min. (Power supply-3.0)VDC
		NPN open collector output	Load current : Max. 30mA, Residual voltage : Max. 0.4VDC
		Voltage output	Load current : Max. 10mA, Residual voltage : Max. 0.4VDC
		Line driver output	Low $\Rightarrow$ Load current : Max. 20mA, Residual : Max. 0.5VDC High $\Rightarrow$ Load current : Max. -20mA, Output voltage : Min. 2.5VDC
	Response time (Rise/Fall)	Totem pole output	Max. 1 μ s
		NPN open collector output	Max. 1 μ s
		Voltage output	Max. 1 μ s
		Line driver output	Max. 0.5 μ s
	Max. Response frequency	300kHz	
	Power supply	• 5VDC ±5% (Ripple P-P: Max. 5%) • 12-24VDC ±5% (Ripple P-P: Max. 5%)	
	Current consumption	Max. 80mA (disconnection of the load), Line driver output: Max. 50mA (disconnection of the load)	
	Insulation resistance	Min. 100M Ω (at 500VDC)	
	Dielectric strength	750VAC 50/60Hz for 1 minute (Between all terminals and case)	
	Connection	Cable outgoing type, 200mm cable outgoing connector type	
Mechanical specification	Starting torque	Shaft Type : Max. 40gf • cm (0.004N • m), Holl Type : Max. 50gf • cm (0.005N • m)	
	Rotor inertia	Max. 40g • cm ² (4 × 10 ⁻⁶ kg • m ²)	
	Shaft loading	Radial : Max. 2kgf, Thrust : Max. 1kgf	
	Max. allowable revolution	(Note2) 5000rpm	
Vibration		1.5mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 2 hours	
Shock		Max. 50G	
Ambient temperature		-10 ~ 70°C (at non-freezing status), Storage: -25 ~ 85°C	
Ambient humidity		35~85%RH, Storage: 35~90%RH	
Protection		IP50 (IEC standard)	
Cable		ø 5mm, 5P, Length : 2m, Shield cable (Line driver output : ø 5mm, 8P)	
Accessory		• Shaft type: ø 6mm coupling standard, ø 8mm coupling (Option) • Hole type : Bracket	
Unit weight		Approx. 120g	
Approval		CE (Except for Line driver output)	

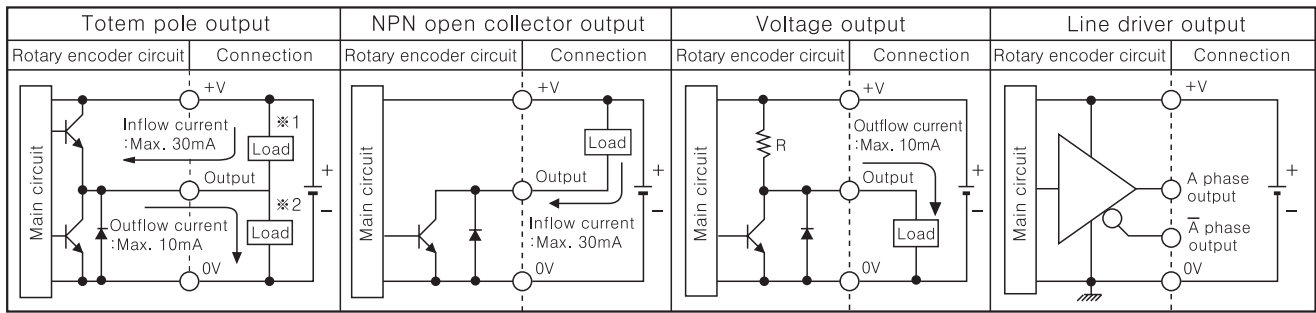
* **(Note1)** '1*' pulse is only for A, B phase (Line Driver output is for A, $\bar{A}$, B, $\bar{B}$ phase)

* **(Note2)** Max. allowable revolution $\geq$ Max. response revolution 【Max. response revolution (rpm) = $\frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec}$ 】

(A) Counter
(B) Timer
(C) Temp. controller
(D) Power controller
(E) Panel meter
(F) Tacho/Speed/Pulse meter
(G) Display unit
(H) Sensor controller
(I) Switching power supply
(J) Proximity sensor
(K) Photo electric sensor
(L) Pressure sensor
(M) Rotary encoder
(N) Stepping motor & Driver & Controller
(O) Graphic panel
(P) Production stoppage models & replacement

E40 Series

Control output diagram

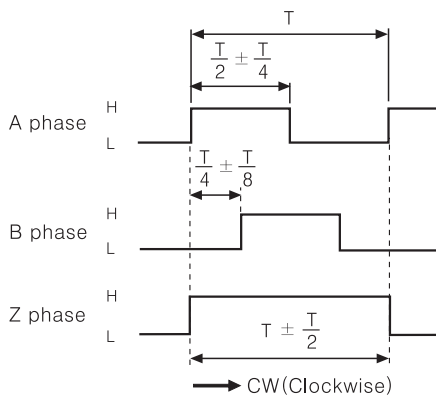


☞ Totem pole output type can be used for NPN open collector output type(*1) or Voltage output type(*2).

☞ All output circuits of A, B, Z phase is same. (Line driver output is A, $\bar{A}$, B, $\bar{B}$, Z, $\bar{Z}$)

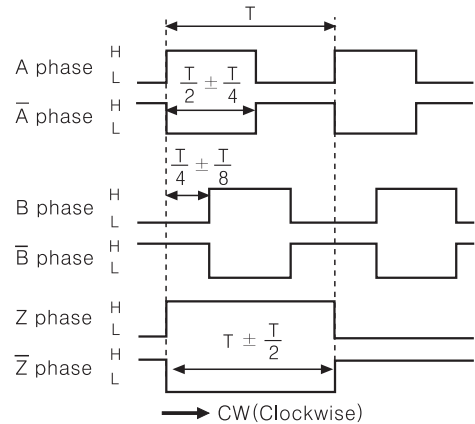
Output waveform

● Totem pole output / NPN open collector output / Voltage output



※ CW : In a view of shaft

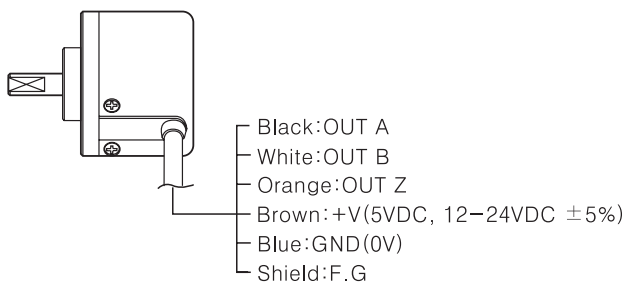
● Line driver output



Connections

Normal type

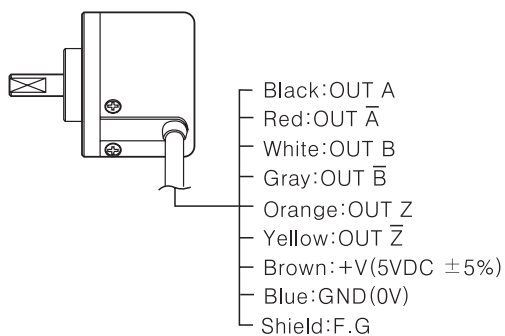
● Totem pole output / NPN open collector output / Voltage output



※ Unused wires must be insulated.

※ The metal case and shield wire of encoder should be grounded(F.G).

● Line driver output

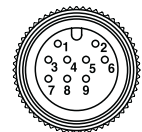


Cable outgoing connector type

● Totem pole output
NPN open collector output
Voltage output



● Line driver output



Totem pole output NPN open collector output Voltage output			Line driver output		
Pin No	Function	Cable color	Pin No	Function	Cable color
①	OUT A	Black	①	OUT A	Black
②	OUT B	White	②	OUT $\bar{A}$	Red
③	OUT Z	Orange	③	+V	Brown
④	+V	Brown	④	GND	Blue
⑤	GND	Blue	⑤	OUT B	White
⑥	F.G	Shield	⑥	OUT $\bar{B}$	Gray
			⑦	OUT Z	Orange
			⑧	OUT $\bar{Z}$	Yellow
			⑨	F.G	Shield

※ F.G(Field Ground): It should be grounded separately.

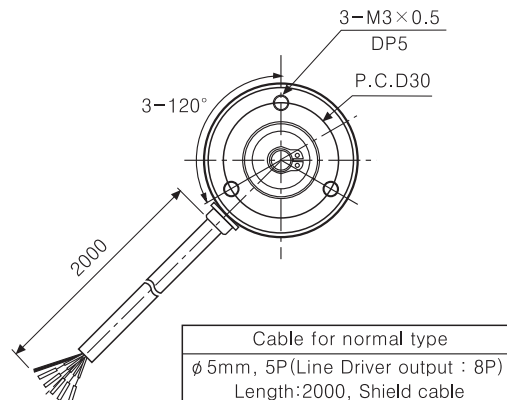
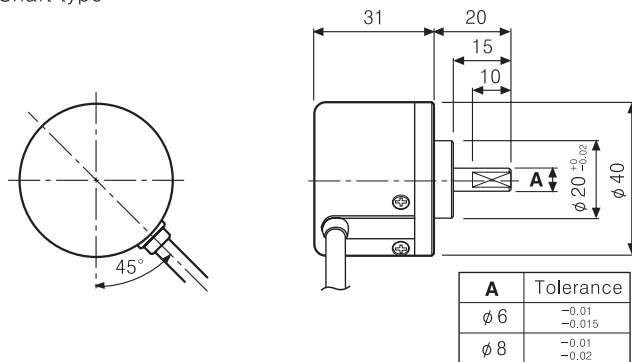
Incremental ϕ 40mm Shaft/Hollow Shaft/Built-in Type

■ Dimensions

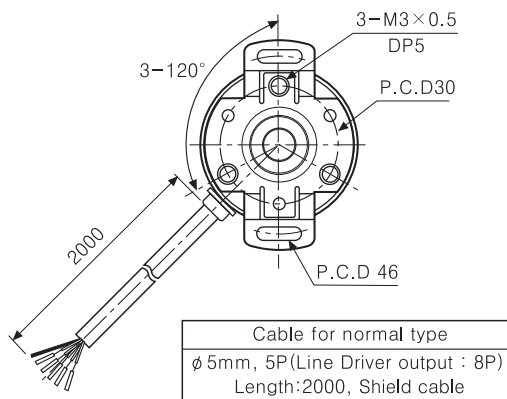
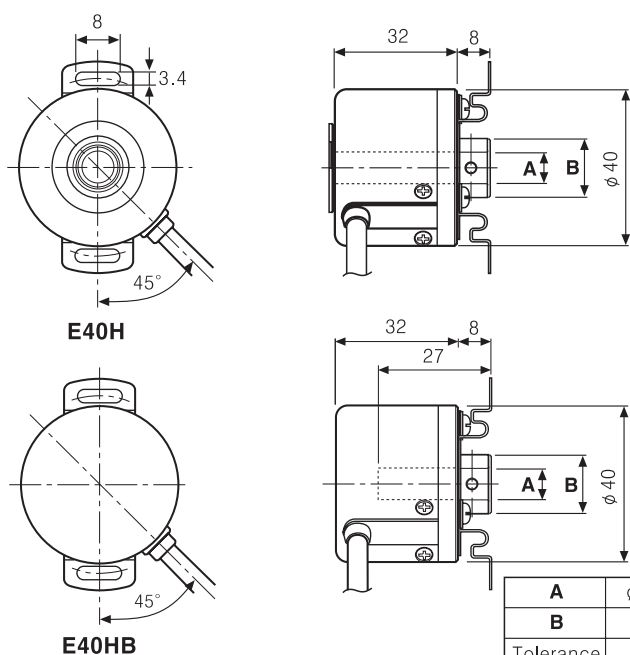
■ Normal type

● Shaft type

(Unit:mm)

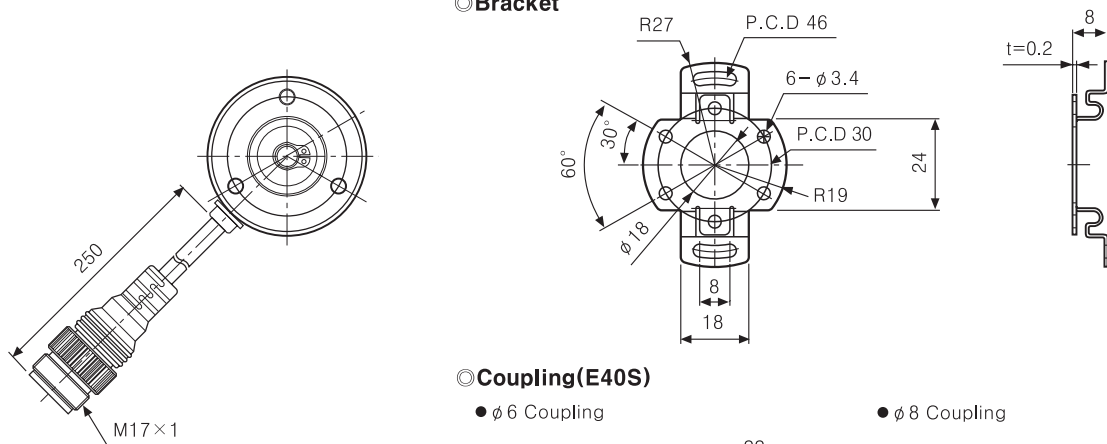


● Hollow shaft / Hollow shaft built-in type



■ Cable outgoing connector type

◎ Bracket

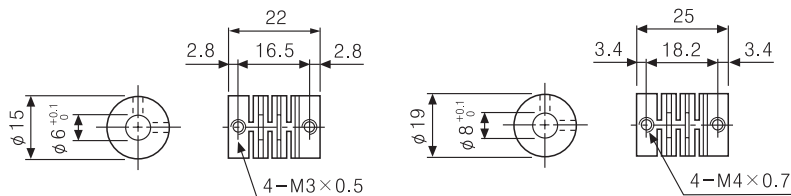


◎ Coupling(E40S)

● ϕ 6 Coupling

● ϕ 8 Coupling

※The connector cable is optional and refer to M-46 for the specification.



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