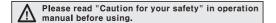
Compact, universal voltage type with built-in amplifier

■ Features

- •Small and universal voltage type.
- Easy installation with LED indicators on product.
- •Able to set the operation mode by switch. (Light ON/Dark ON)
- •Able to check the operation status by stable LED indicator and output LED indicator.
- •Built-in IC photo diode for ambient light and electrical noise.







Specifications

•AC/DC power, Relay contact output

Model		BEN10M-TFR	BEN5M-MFR	BEN3M-PFR	BEN300-DFR	
Sensing type		Transmitted beam	Retroreflective (Standard type)	Retroreflective (with polarizing filter)	Diffuse reflective	
Sensing distance		10m	(*1) 0.1 ~ 5m	(*1) 0.1 ~ 3m	(*2) 500mm	
Sensin target		Opaque materials of Min. ϕ 16mm	Opaque materials of Min. Ø 60mm		Transparent, Translucent, Opaque materials	
Hysteresis					Max. 20% at rated setting distance	
Response time		Max. 20ms				
Power supply		24-240VAC ±10% 50/60Hz, 24-240VDC ±10% (Ripple P-P:Max. 10%)				
Power consumption		Max. 3VA				
Light source		Infrared LEI	(modulated)	Red LED (Modulated : 660nm)	Infrared LED (modulated)	
Sensitivity adjustment		———— Adjustable VR				
Operation mode		Light ON or Dark ON mode selectable by switch				
Control output		Relay contact output(Contact capacity : 30VDC 3A resistive load, 250VAC 3A resistive load, Relay contact composition : 1c)				
Relay life cycle		Mechanically: Min. 50,000,000, Electrically: Min. 100,000				
Light receiving element		Built-in IC type photo diode				
Indicator		Operation indicator: Orange, Stable indicator: Green (The orange lamp on Emitter of transmitted beam type is for power indication)				
Connection		Outgoing cable				
Insulation resistance		Min. 20MΩ (at 500VDC)				
Noise strength		$\pm 1000 \mathrm{V}$ the square wave noise(pulse width:1 μ s) by the noise simulator				
Dielectric strength		1000VAC 50/60Hz for 1minute				
Vibration -	Mechanical	1.5mm amplitude at frequency of 10 \sim 55Hz in each of X, Y, Z directions for 2 hours				
	Malfunction	1.5mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 10 minutes				
Shock	Mechanical	500m/s ² (50G) in X, Y, Z directions for 3 times				
SHOCK	Malfunction	100m/s ² (10G) in X, Y, Z directions for 3 times				
Ambient illumination		Sunlight: Max. 11,000/x, Incandescent lamp: Max. 3,000/x				
Ambient temperature		-20 ~ +65 ℃ (at non-freezing status), Storage: -25 ~ +70 ℃				
Ambient humidity		35 ~ 85%RH, Storage : 35 ~ 85%RH				
Material		Case: ABS, Lens cover: Acrylic, Lens: Acrylic				
Protection		IP65(IEC standard)				
Cable		∅ 6.0mm, 5P, Length : 2m				
Accessory	Individual		Reflector			
	Common	Adjustment driver, Fixing bracket, Bolts/Nuts				
Unit weigh	t	Approx. 354g	Approx	x. 208g	Approx. 195g	

^{(★1)}** Sensing distance of retroreflective type is against MS-2 it shows settable range between reflector and photo sensor and it is able to detect a target within under 0.1m.

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^{*(*2)} It is for Non-glossy white paper (100×100mm).

Universal Voltage Type with Built-in Amplifier

•DC power, Solid state output

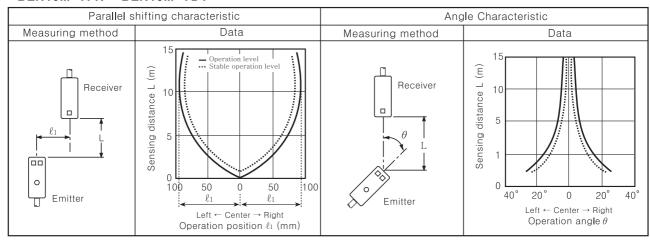
Model	BEN10M-TDT	BEN5M-MDT	BEN3M-PDT	BEN500-DDT		
Sensing type	Transmitted beam	Retroreflective	Retroreflective (with polarizing filter)	Diffuse reflective		
Sensing distance	10m	(*1) 0.1 ~ 5m	(*1) 0.1 ~ 3m	(*2) 500mm		
Sensing target	Opaque materials of Min. ø16mm	Opaque materials of Min. Ø60mm		Transparent, Translucent, Opaque materials		
Hysteresis				Max. 20% at sensing distance		
Response time	Max. 1ms					
Power supp l y	12-24VDC ±10% (Ripple P-P : Max. 10%)					
Current consumption	Max. 40mA					
Light source	Infrared LF	ED(modulated)	Red LED (modulated, 660nm)	Infrared LED(modulated)		
Sensitivity adjustmer	———— Adjustable VR					
Operation mode	Light ON or Dark ON selectable by switch					
Control output	●NPN/PNP output simultaneously • NPN open collector output ☞ Load voltage:Max. 30VDC, Load current:Max. 200mA, Residual voltage:Max. 1V • PNP open collector output ☞ Output voltage:Min. (Power supply—2.5)V, Load current:Max. 200mA					
Protection circuit	Reverse polarity protection, Short-circuit protection					
ight receiving eleme	Built-in IC type photo diode					
Indicator	Operation indicator : Orange, Stable indicator : Green (The orange lamp on Emitter of transmitted beam type is for power indication)					
Connection	Outgoing cable					
nsulation resistance	Min. 20MΩ (at 500VDC)					
Noise strength	$\pm 240 \mathrm{V}$ the square wave noise(pulse width:1 μ s) by the noise simulator					
Dielectric strength	1000VAC 50/60Hz for 1minute					
/ibration	1.5mm amplitude at frequency of 10 \sim 55Hz in each of X, Y, Z directions for 2 hours					
Shock	500m/s ² (50G) in X, Y, Z directions for 3 times					
Ambient i ll umination	Sunlight: Max. 11,000/x, Incandescent lamp: Max. 3,000/x					
Ambient temperature	-20 ~ +55℃ (at non-freezing status), Storage: -25 ~ +70℃					
Ambient humidity	35 ~ 85%RH, Storage : 35 ~ 85%RH					
Protection	IP65 (IEC standard)					
Material	Case: ABS, Lens cover: Acrylic, Lens: Acrylic					
Cable	φ 6.0mm, 4P, Length : 2m					
Accessory Individua	———— Reflector (MS-2)					
Commor	Adjustment driver, Fixing bracket, Bolts/Nuts					
Approval	(€					
	Approx. 342g	Appr				

^{(*1)}**Sensing distance of retroreflective type is against MS−2, it shows settable range between reflector and photo sensor and it is able to detect a target within under 0.1m.

■ Feature data

Transmitted beam

●BEN10M-TFR ●BEN10M-TDT



(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/ Speed/ Pulse meter

> (G) Display unit

(H) Sensor controller

(I) Switching power supply

Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

(P) Production stoppage models & replacement

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^(*2)It is for Non-glossy white paper (100×100mm).

BEN Series

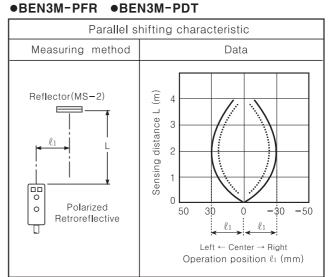
■ Feature data

Retroreflective

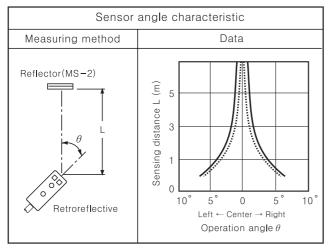
●BEN5M-MFR ●BEN5M-MDT

Parallel shifting characteristic Measuring method Operation level Stable operation level Reflector(MS-2) (m) Sensing distance 3 e e 0 -100100 50 -50 ℓ_1 Retroreflective $\mathsf{Left} \leftarrow \mathsf{Center} \rightarrow \mathsf{Right}$ Operation position ℓ_1 (mm)

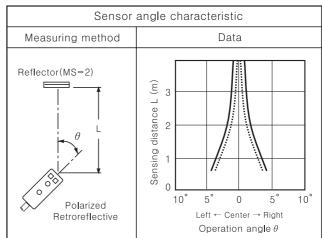
OPolarized retroreflective



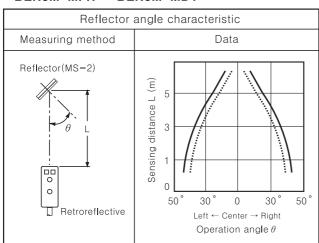
●BEN5M-MFR ●BEN5M-MDT



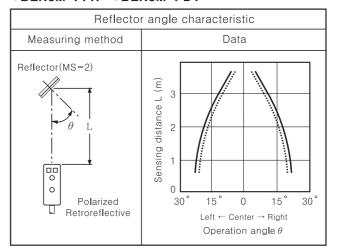
●BEN3M-PFR ●BEN3M-PDT



●BEN5M-MFR ●BEN5M-MDT



●BEN3M-PFR ●BEN3M-PDT



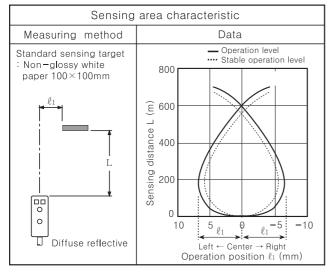
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Universal Voltage Type with Built-in Amplifier

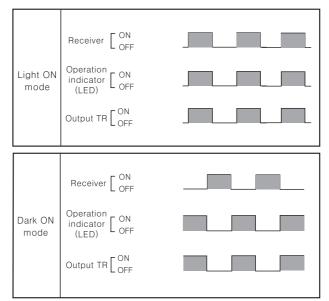
■ Feature data

ODiffuse reflective

●BEN300-DFR ●BEN300-DDT



Operation mode



(A)

Counter

(B) Timer

(C) Temp.

Power controller

(E)

Panel

Tacho/ Pulse

(G) Display

Sensor controller

Switching power supply

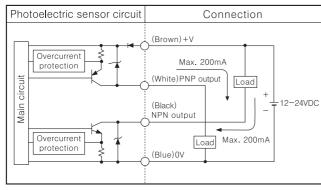
Proximity

unit

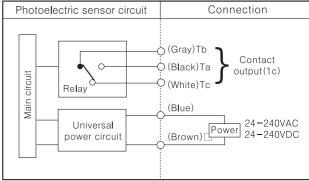
sensor

Control output diagram

DC voltage(NPN/PNP 2 output)



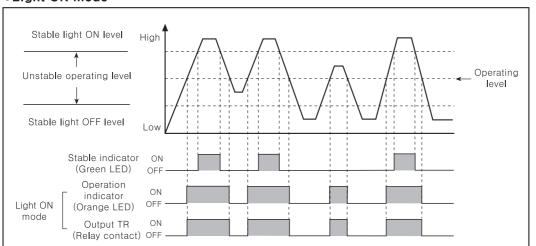
Universal voltage(Relay contact output)



XIIn case of product with the output protection device, if terminals of control output are short circuited or overcurrent condition is existed, the control output will turn off due to protection circuit.

Operation mode and timing chart

Light ON mode



^{*}The waveform of output TR and operation indicator are the state of operation for Light ON mode, but in case of Dark ON mode, it operates as reverse against Light ON mode.

(K) Photo electric sensor

Pressure sensor

Rotary

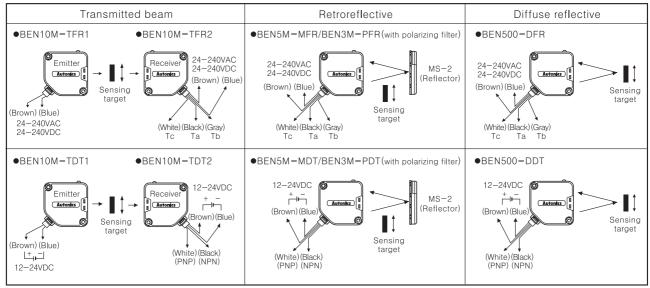
(N) Stepping motor & Driver & Controller

Graphic

Production stoppage models & replacement

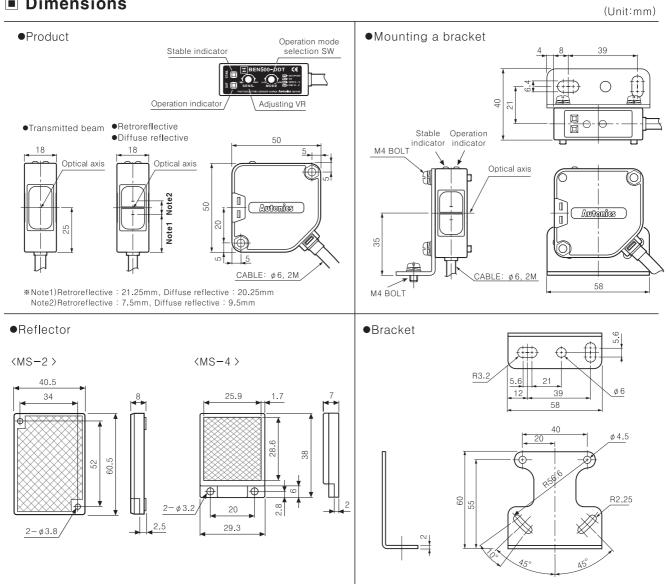
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Connections



***Unused line must be insulated.**

Dimensions



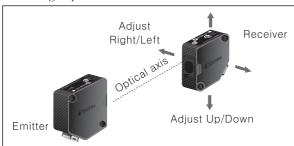
Autonics K - 39

Universal Voltage Type with Built-in Amplifier

■ Mounting and sensitivity adjustment

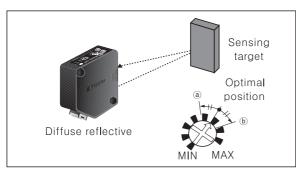
OTransmitted beam type

- Supply the power to the photoelectric sensor, after set the emitter and the receiver facing each other.
- 2. Set the receiver in the middle of the operation range of indicator adjusting the receiver or the emitter right and left, up and down.
- 3. Adjust up and down direction as the same.
- 4. After adjustment, check the stability of operation putting the object at the optical axis.
- *If the sensing target is translucent body or smaller than \$\phi\$16mm, it can be missed by sensor cause light passed.



ODiffuse reflective type

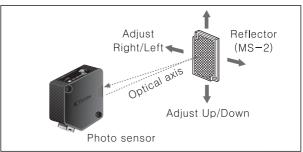
- 1. Adjust sensitivity regarding the effectiveness of behind object or mounting side.
- 2. Set the target at a position to be detected by the beam, then turn the adjuster until position ⓐ in the middle of the operation range of indicator from min. position of the adjuster.
- 3. Take the target out of the sensing area, then turn the adjuster until position (b) where the indicator turns on. If the indicator does not turn on, Max. position is position (b).
- 4. Set the adjuster at the middle of two switching position ⓐ, ⓑ.
- *The sensing distance indicated on specification chart is against 100×100mm of non-glossy white paper. Be sure that it can be different by size, surface and gloss of target.



©Retroreflective type

- 1. Supply the power, after set the photoelectric sensor and the reflector(MS-2) facing each other.
- 2. Set the Photoelectric sensor in the middle of the position in the middle of the operation range of indicator adjusting the reflector or the sensor right and left, up and down.

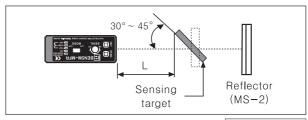
- 3. Adjust up and down direction as the same.
- 4. After adjustment, check the stability of operation putting the object at the optical axis.



- *If use more than 2 photoelectric sensors in parallel, the space between them should be more than 30cm.
- *If reflectance of target is higher than non-glossy white paper, it might cause malfunction by reflection from the target when thr target is near to photoelectric sensor. Therefore put enough space between the target and photoelectric sensor or the surface of target should be installed at an angel of 30 °~45 °against optical axis.

(When detecting target with high reflectance near by, photoelectric sensing with the polarizing filter should be used.)

*Sensitivity adjustment : Please see the diffuse reflective type.

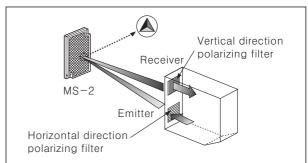


*If the mounting place is too small, please use MS-4 instead of MS-2 for same sensing distance.



ORetroreflective type(With polarizing filter)

The light passed through the polarizing filter of emitter reaches to MS-2 converting as horizontal direction, it reaches to photodetector through the filter of receiver converting as vertical by MS-2 function. Even it can detect normal mirror.



(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/ Speed/ Pulse meter

> (G) Display unit

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

(P) Production stoppage models & replacement

Autonics K-40