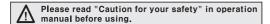
Terminal type photoelectric sensor for long distance

■ Features

- •Built-in sensitivity adjustment VR
- •Timer: ON Delay, OFF Delay, One-shot Delay
- •NPN/PNP open collector output(DC power type)
- •Self-diagnosis function
 - (Green LED is lighted in stable level.)
- •Built-in reverse power polarity protection and overcurrent protection circuit.
- •Wide range of power supply: Common use of 24-240VDC/24-240VAC
- •Waterproof structure: IP66 (IEC standard)









Specifications

Universal voltage type

*The power supply is upgraded.

	Standard type	BX15M-TFR	BX5M-MFR	BX3M-PFR	BX700-DFR			
Model	With Timer	BX15M-TFR-T	BX5M-MFR-T	BX3M-PFR-T	BX700-DFR-T			
Sensin	g type	Transmitted beam	Retroreflective(Standard type)	Retroreflective(polarizing filter)	Diffuse reflective			
	g distance	15m	(*1) 0.1 ~ 5m(MS-2)	(*2) 0.1 ~ 3m(MS-3)	(* 3) 700mm			
Sensin	g target	Opaque materials of Min. ∮15mm	Opaque materials of Min. Ø60mm		Transparent, Translucent, Opaque material			
Hystere	sis				Max. 20% at rated setting distance			
Respor	ise time	Max. 20ms						
Power:	supply	24-240VAC ±10% 50/60Hz, 24-240VDC ±10% (Ripple P-P:Max. 10%)						
Current	consumption	Max. 3VA						
Light so	ource	Infrared LEI	Infrared LED (Modulated) Red LED (Modulated: 660nm) Infrared LED (Modula					
Sensitiv	ity adjustment	Adjustable by VR						
Operati	on mode	Selectable Light ON or Dark ON by slide switch						
Control	output	Relay contact output © Contact capacity: 30VDC 3A, 250VAC 3A at resistive load, Contact composition: 1c(SPDT)						
Relay li	fe cyc l e	Mechanically: Min. 50,000,000, Electrically: Min. 100,000						
Self-d	agnosis output	Green LED turns on at unstable operation						
Timer f	unction	Selectable ON Delay, OFF Delay, One Shot Delay by slide switch [Delay Time : 0.1 ~ 5sec(VR adjustable)]						
Indicat	or	Operation indicator : Yellow LED, Self-diagnosis indicator : Green LED						
Connec	ction	Terminal connection						
Insulati	on resistance	Min. 20MΩ (at 500VDC)						
Insulati	on type	Double insulation						
Noise s	trength	±1,000V the square wave noise(pulse width:1μs) by the noise simulator						
Dielect	ric strength	1500VAC 50/60Hz for 1minute						
Impulse dielectric strength		1kV(Generator: 1.2/50μs, Source impedence: 500Ω, Source energy: 0.5J)						
Vibratio	Mechanical	1.5mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 2 hours						
Vibratic	Malfuntion	1.5mm amplitu	1.5mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 10 minutes		for 10 minutes			
Shock	Mechanical	500m/s ² (50G) in X, Y, Z directions for 3 times						
Silver	Malfuntion	100m/s ² (10G) in X, Y, Z directions for 3 times						
Ambier	ıt i ll umination	Sunlight: Max. 11,000/x, Incandescent lamp: Max. 3,000/x						
Ambier	it temperature	-20 ~ +65℃ (at non-freezing status), Storage: -25 ~ +70℃						
Ambier	it humidity	35 ~ 85%RH, Storage : 35 ~ 85%RH						
Protect	ion	IP66 (IEC standard)						
Material		Case: ABS, Lens: Acrylic						
Access	Individual							
Access	Common	Adjustment driver, Fixing bracket, Bolts/Nuts						
Approval		(É						
Unit we	ight	TFR: Approx. 198g, TFR-T: Approx. 203g	MFR: Approx. 126g, MFR-T: Approx. 131g	PFR: Approx. 130g, PFR-T: Approx. 134g	DFR : Approx. 110g, DFR-T : Approx. 115g			

^{※(*1)}It is same when using MS-4 and it is able to detect under 0.1m.

K - 41**Autonics**



^{※(*2)}Using MS-2, sensing distance will be 0.1~2m, it is able to detect under 0.1m.

^{*(*3)}It is for Non-glossy white paper(200×200mm)

Universal Voltage with Built-in Amplifier(Terminal type)

■ Specifications

●DC power type

***It** is upgraded as NPN, PNP synchronous output type.

	Standard type	BX15M-TDT	BX5M-MDT	BX3M-PDT	BX700-DDT		
Model With Timer		BX15M-TDT-T	BX5M-MDT-T	BX3M-PDT-T	BX700-DDT-T		
Sensing type		Transmitted beam	mitted beam Retroreflective Retroreflective (Standard type) (Polarizing filter)		Diffuse reflective		
Sensin	g distance	15m	(*1) 0.1 ~ 5m(MS-2)	(*2) 0.1 ~ 3m(MS-3)	(*3) 700mm		
Sensin	g target	Opaque materials of Min. ø15mm	Opaque materials of Min. ∮60mm	Opaque materials of Min. ∮60mm	Transparent, Translucent Opaque material		
Hyster	esis				Max. 20% at rated setting distance		
Respo	nse time	Max. 1ms					
Power	supply	12-24VDC ±10% (Ripple P-P:Max. 10%)					
Curren	t consumption	Max. 40mA Max. 30mA					
Light s	ource	Infrared LEI	O(Modulated)	Infrared LED (Modulated)	Infrared LED (Modulated)		
Sensiti	vity adjustment	Adjustable by VR					
Operat	ion mode	Selectable Light ON or Dark ON by slide switch					
Control output		• NPN open collector output Doad voltage: Max. 30VDC, Load current: Max. 200mA, Residual voltage: Max. 1V at 200mA, Max. 0.4V at 16mA • PNP open collector output(Yellow LED) Output voltage: Min. power supply-2.5V, Load current: Max. 200mA					
Self-diagnosis output		NPN open collector output Doad voltage: Max. 30VDC, Load current: Max. 50mA, Residual voltage: Max. 1V at 50mA, Max. 0.4V at 16mA					
Protection circuit		Reverse polarity protection, Overload & short circuit pretection					
Timer 1	function	Selectable ON Delay, OFF Delay, One Shot Delay by slide switch [Delay Time: 0.1 ~ 5sec(VR adjustable)]					
Indicat	tor	Operation indicator : Yellow LED, Self-diagnosis indicator : Green LED					
Conne	ction	Terminal connection					
Insulat	ion resistance	Min. 20MΩ (at 500VDC)					
Noise strength		$\pm 240 \mathrm{V}$ the square wave noise (pulse width:1 μ s) by the noise simulator					
Dielect	ric strength	1000VAC 50/60Hz for 1minute					
Vibration		1.5mm amplitude at frequency of 10 \sim 55Hz in each of X, Y, Z directions for 2 hours					
Shock		500m/s ² (50G) in X, Y, Z directions for 3 times					
Ambie	nt i ll umination	Sunlight: Max. 11,000/x, Incandescent lamp: Max. 3,000/x					
Ambient temperature		-20 ~ +65 °C (at non-freezing status), Storage : -25 ~ +70 °C					
Ambient humidity		35 ~ 85%RH, Storage : 35 ~ 85%RH					
Protection		IP66(IEC standard)					
Material		Case: ABS, Lens cover: Acrylic, Lens: Acryl					
Access	Individual	refrector (Fig. 2)					
	Common	Adjustment driver, Fixing bracket, Bolts/Nuts					
Approval		C€					
	eight	Approx. 212g	Approx. 124g	Approx. 142g	Approx. 117g		

^{※(*1)}It is the same when using MS-4 and it is able to detect under 0.1m.

(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/ Speed/ Pulse meter

> (G) Display unit

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

(P) Production stoppage models & replacement

Autonics K-42

^{※(*2)}Using MS-2, sensing distance will be 0.1~2m, it is able to detect under 0.1m.

^{*(*3)}It is for Non-glossy white paper(200 \times 200mm).

BX Series

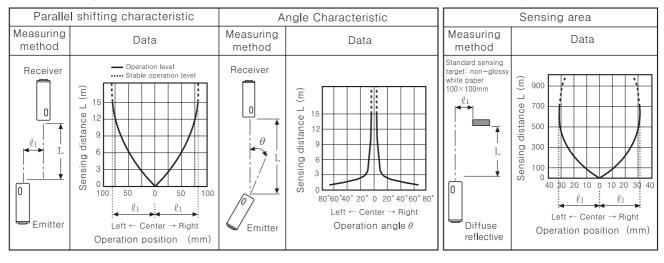
■ Feature data

OTransmitted beam

- ●BX15M-TFR / BX15M-TFR-T
- ●BX15M-TDT / BX15M-TDT-T

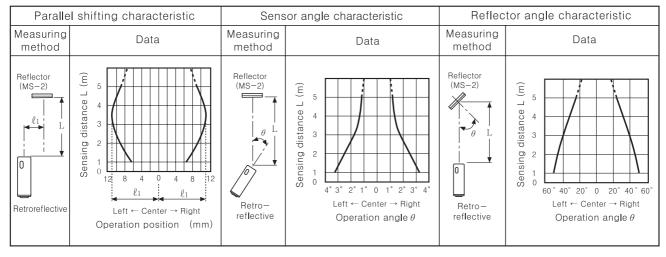
ODiffuse reflective

- ●BX700-DFR / BX700-DFR-T
- ●BX700-DDT / BX700-DDT-T



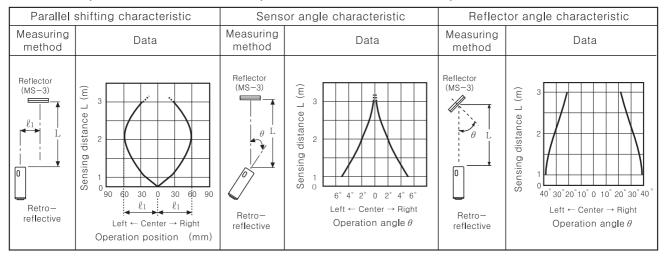
Retroreflective

●BX5M-MFR / BX5M-MFR-T ●BX5M-MDT / BX5M-MDT-T ●BX5M-MDT-P / BX5M-MDT-TP



Polarized retroreflective

●BX3M-MFR /BX3M-MFR-T ●BX3M-MDT / BX3M-MDT-T ●BX3M-MDT-P / BX3M-MDT-TP



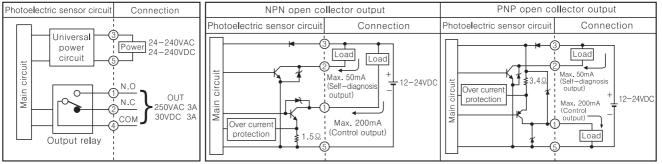
K-43 Autonics

Universal Voltage with Built-in Amplifier(Terminal type)

■Control output diagram

OUniversal voltage

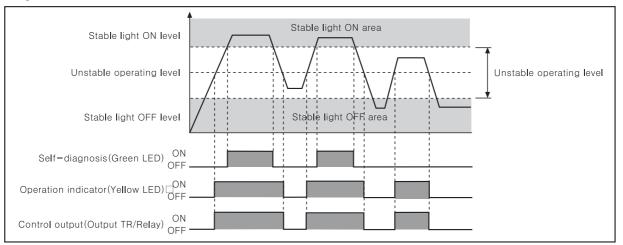
ODC voltage



^{*}In case of product with the output protection device, if terminals of control output are short—circuited or overcurrent condition is existed, the control output will turn off due to protection circuit.

Operation mode and timing diagram

●Light ON mode



^{*}Operation for Dark ON mode is opposed to above chart indication for Light ON mode.

■ Timer mode

	0147		N 01 1 11 1	
Timer mode	SW position		Status of light	ON III III
Timer mode	S1	S2	Operation mode	OFF -
NORMAL MODE	ON	ON -	Light ON	ON OFF
NORMAL MODE			Dark ON	OUT ON (Control output) OFF
ONE SHOT DELAY	ON	OFF	Light ON	OUT ON (Control output) OFF
MODE			Dark ON	OUT ON (Control output) OFF
ON DELAY MODE	OFF	ON	Light ON	OUT ON T (Control output) OFF
ON DELAY MODE			Dark ON	OUT ON T T T T T T T T T T T T T T T T T T
OFF DELAY MODE	OFF	055	Light ON	OUT ON T T T T T T T T T T T T T T T T T T
OFF DELAY MODE		OFF	Dark ON	OUT ON (Control output) OFF

※T: Time set by timer VR.

(A) Counter

(B) Timer

> (C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/ Speed/ Pulse meter

(G) Display unit

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

Production stoppage models & replacement

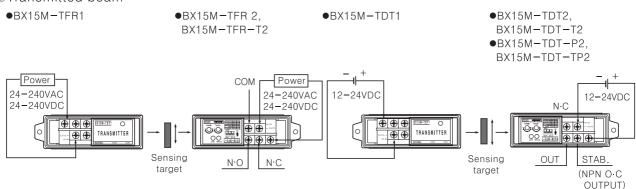
Autonics K-44

^{*}To prevent from the misoperation, output of units keeps the state of OFF for 0.5sec. after power ON.

BX Series

Connections

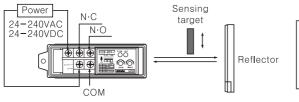
©Transmitted beam

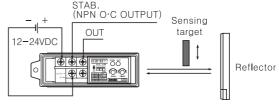


©Retroreflective / Retroreflective with polarizing filter

- ●BX5M-MFR, BX5M-MFR-T
- ●BX3M-PFR, BX3M-PFR-T

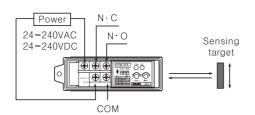
- ulletBX5M-MDT, BX5M-MDT-T ulletBX5M-MDT-P, BX5M-MDT-TP
- ●BX3M-PDT, BX3M-PDT-T ●BX3M-PDT-P, BX3M-PDT-TP



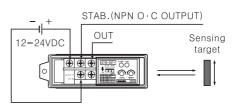


ODiffuse reflective

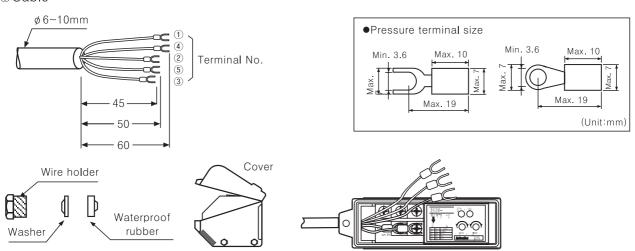
●BX700-DFR, BX700-DFR-T



- ●BX700-DDT, BX700-DDT-T
- ●BX700-DDT-P, BX700-DDT-TP



OCable



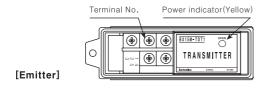
- *On servicing wire, connect wire on terminal as above figure.
- **Select the round wire with the size of ϕ 6 ~10mm for the waterproof and tighten the cable holder by torque of 1.0 to 1.5N m.
- *On servicing wire, tighten screw of terminals by torque of 0.8N m.
- $\mbox{\em \%On}$ mounting the cover, tighten the cover nut by torque of $0.3\mbox{\em \sim}0.5\mbox{N}$ m.

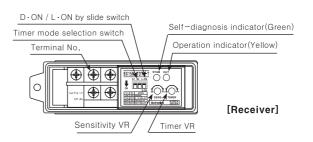
K-45 Autonics

Universal Voltage with Built-in Amplifier(Terminal type)

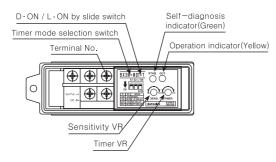
■ Front panel identification

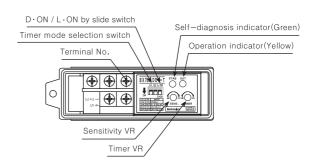
©Transmitted beam





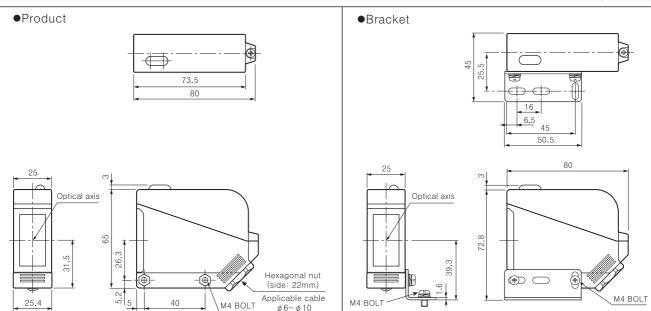
©Retroreflective / Retroreflective with polarizing filter ©Diffuse reflective

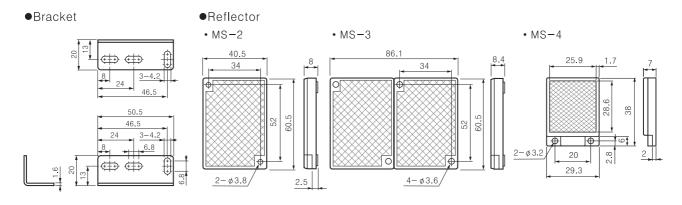




*There are no Timer mode selection switch and Timer VR in type without Timer function.

■ **Dimensions** (Unit:mm)





(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel

(F) Tacho/ Speed/ Pulse

meter

(G) Display unit

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

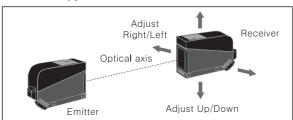
(P) Production stoppage models & replacement

Autonics K-46

Mounting and sensitivity adjustment

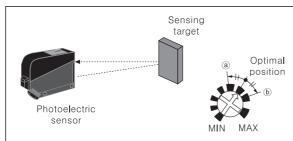
OTransmitted beam type

- 1. Supply the power to the photoelectric sensor, after set the emitter and the receiver facing each other.
- 2. Set the receiver in center of position in the middle of the operation range of indicator adjusting the receiver or the emitter right and left, up and down.
- 3. Adjust up and down direction as the same.
- 4. After adjustment, check the stability of operation putting the object at the optical axis.
- *If the sensing target is translucent body or smaller than \$\phi 15mm\$, it can be missed by sensor cause light penetrate it.
- *Sensitivity adjustment : Please see the diffuse reflective type.



ODiffuse reflective type

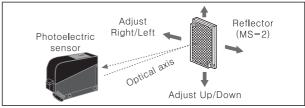
- 1. The sensitivity should be adjusted depending on a sensing target or mountin place.
- 2. Set the target at a position and turn sensitivity adjuster from minimum sensitivity position slowly, confirm position (a) in the middle of the operation range of indicator and self diagnosis indicator (Green LED) is OFF.
- 3. If turn adjuster higher slowly in state of removed target, the operation indicator (Yellow LED) will be OFF and self diagnosis indicator (Green LEd) will be ON. Confirm this position as (a).
 - [When self diagnosis indicator(Green LED) and operation indicator(Yellow LED) are OFF, the Max. sensitivity position will be **(b)**.]
- 4. Set the adjuster at the center of two switching position (a), (b).
- **Above sensitivity adjustment is when it is the state of Light ON mode. If it is the state of Dark ON mode, operation indicator(Yellow LED) will be opposite.



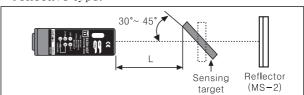
*The sensing distance indicated on specification chart is against 200×200mm of non-glossy white paper. Be sure that it can be different by size, surface and gloss of target.

©Retroreflective type

- 1. Supply the power to the photoelectric sensor, after set the photoelectric sensor and the reflector(MS-2) facing each other.
- 2. Set the photoelectric sensor in the middle of the operation range of indicator adjusting the reflector or the sensor right and left, up and down.
- 3. Adjust up and down direction as the same.
- 4. After adjustment, check the stability of operation putting the object at the optical axis.
- *If use more than 2 photoelectric sensors in parallel, the space between them should be more than 30cm.



- *If use more than 2 photoelectric sensors in parallel, the space between them should be more than 30cm.
- **If reflectance of target is higher than non-glossy white paper, it might cause malfunction by reflection from the target when the target is near to photo sensor. Therefore put enough space between the target and photoelectric sensor or the surface of target should be installed at an angle of 30° ~ 45° against optical axis. (When detecting target with high reflectance near by, photoelectric sensor with the polarizing filter should be used.)
- *Sensitivity adjustment : Please refer to the diffuse reflective type.

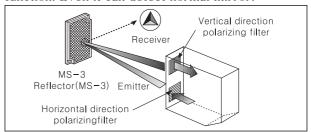


*If the mounting place is too small, please use MS-4 instead of MS-2 for same sensing distance.



©Retroreflective type(With polarizing filter)

The light passed through the polarizing filter of emitter reaches to MS-3 converting as horizontal direction, it reaches to photodetector through the filter of receiver converting as vertical by MS-3 function. Even it can detect normal mirror.



K-47 Autonics