

## SHIMAX THYRISTOR SYNGLE-PHASE **POWER REGULATOR**

## MP11 SERIES

#### **Cum Feedback Function**



#### **Special Features**

- Setting function by operating the keys on the front panel
- 7-segment LED display of setting contents, input/output values, etc.
- Control input signal: Multi-input of current, voltage, contact, and voltage pulse
- Feedback function is equipped as a standard (constant voltage, constant current, constant power, and voltage square)
- 🌒 Many kinds of alarm outputs are equipped as a standard, such as alarm of current failure, alarm of snapped heater wires
- Switching over either to phase control method or to zero-cross switching cycle operation control method
- Control voltage: Free voltage of 100~240V AC
- Choice of RS485 communication: MODBUS or SHIMAX standard protocol (option)

#### **Specification**

Control Method

: Phase control with a feedback function
——constant voltage, constant current, constant power, voltage square

Control without a feedback function
—— angle, voltage square, ZC (\*1)
angle + ZC (\*1), voltage square + ZC (\*1)

■ Current-carrying Capacity: 18 types: 1A~10A (1A calibration), 20A, 30A, 50A, 70A, 100A, 150A, 200A, 300A

■ Control Range of Output Voltage: 0~98%

■ Lowest Load Capacitt : 0.5A (rated current 100A and below) 1.0A (rated current 150A and above)

: Phase control Resistive load, Inductive load (primary side of the transformer: magnetic flux density 1.25T and below)

Phase-ZC control Resistive load ZC control Constant resistive load

■Input Accuracy of Control value : (1.0% 1 digit) 2% in case of 0~1V, 0~4mA range

■Display

Applicable Load

■Power Supply
Control circuit power voltage: 100~240V 10%AC 50/60Hz Main circuit power voltage :  $15{\sim}240\mathrm{V}$   $10\%\mathrm{AC}$   $50/60\mathrm{Hz}$ 

■ Power Supply Frequency : 50/60Hz automatic discrimination

■Control Input (Multi-input): Current  $4\sim20$ ,  $0\sim20$ mA DC receiving impedance  $165\Omega$  Voltage  $1\sim5$ ,  $0\sim5$ V DC input impedance  $15k\Omega$  No-voltage contact (open collector is chosen) sink load 1mA/5V

Voltage pulse 12V (SSR drive voltage) input impedance  $15k\Omega$ 

: Current voltage 1 / (power supply frequency x 2) s ■Input Sampling Cycle

Contact\_voltage pulse two-position control 2ms proportional control 0.5~120.0s

: 7-segment green LED 1 digit red LED 4 digits (character height 10mm)

Display light green (RUN) light-out-standby blinking-man

light-on - automatic

Red (SYS)

Refer to Table of Alarm Function Red (OC) Red (HB)

■Cooling : 100A and below natural cooling 150A and above compulsory air-cooling

: Control (operation) input, control power supply frequency, load voltage, load current, load power, internal temperature, VR1~VR3 position, Monitor

load impedance

Functions Equipped as Standard: Power-on wait, soft-start, slow-up, slow-down, higher or lower limit of

grade, manualcurrent limit at the time of starting, input offset compensation, input gain compensation, alarm output 2 points, DI 2 points, many kinds of alarms

■Alarm Type

Character Display: burnt-out fuse, frequency failure, stop of a fan, current failure, trouble

of elements, voltage failure, abnormal internal temperature

Light: Current limit, current alarm OC light-on, snapped heater wires HB light-on

Alarm Output : 2 points in common, rating 1A 240V AC resistive load

: Operation by using three keys 

on the front panel Setting

■Protection of elements : Digital gate breaker circuit against current failure (120% of the rated value) or immediately-cut fuse (option)

■ Protection of internal Overheat: Operation stops in response to the alarm of abnormal internal temperature

: 2 points operation mode (RUN-STBY), control mode (AUTO-MANU), Control method (phase-ZC), key-lock (ON-OFF)

Option

: Cum alarm output ■Immediately-cut Fuse

: 1~3 sets ■Variable Resistor

■Communication

Communication Type : EIA standard in conformity to RS-485

Communication Mode : Two-channel half-duplex multi-drop (bus) mode

Synchronous Mode : Start-stop synchronization

500m max. (depending on environmental conditions) Communication Distance Communication Speed: 1200, 2400, 4800, 9600,19200bps (default 9600)

: START / 1bit STOP/1.2bit DATA / 7.8bit ■Data format

PARITY / non.odd.eve (default 7N1)

Slave Address : 1~255 (default 1)

■Error Detection

: Chosen from the following: none, addition, addition 2's complement, exclusive disjunction,

CRC-16, LRC (default none)

Flow Control

Delay : 1~500ms step1 (default 20) ■Communication Code : ASCII code or binary code

: SHIMAX standard protocol or MODBUS-ASCII, MODBUS-RTU protocol ■Protocol

■Terminal Impedance : 120 \Omega (external resistor termnation)

Maximum Number of Units

to be connected: 32 units (a host included, depending on environmental conditions)

■Isolation : Isolated from any other input / output and power supply

**General Specification** 

Data storage : Non-volatile memory (EEPROM)

■Use Environment condition : Temperature -10  $\sim$  55  $^{\circ}$ C(Guaranteed range for operation 0  $\sim$  40  $^{\circ}$ C)

Humidity 90%Rh or below (No condensation) Altitude 2000m above see level max.

Category II Pollution degree 2

: -20~65°C Storage Temperature

■Input Noise Ratio of Rejection: Normal 50dB and above Common 100dB and above

Insulation Resistance

: Between control-input and power supply 20M and above (500V DC)
Between power supply and chassis 20M and above (500V DC)
Between control-input and operation-output 20M and above (500V DC)

: Between control-input and chassis 500V AC per minute ■Withstand Voltage

Between power supply and chassis 2000V AC per min Between control-input and operation output 2300V AC per minute

■Withstand Impulse Noise: Power supply normal/common mode 100ns/1us 1500V or above

■ Reaction to Power failure: Power failure of approx. 3ms or less is ignored. When it continues

for more than 3ms, operation resumes by the function of soft-start after the output becomes 0%.

: 5mm or more on the right and left sides, 100mm or more on the up and bottom sides (No heaters should not be installed under this regulator.) Set-up space

■External Dimension : Refer to Drawings of External Dimension

■ Mounting : Vertical mounting

Weight : Refer to Dimension Table

※1 Zero-cross switching cycle operation

#### ■Table of Alarm Function

Alarm Type Control Meth		Method Alarm D		Alarm Output Operational Condition at		Causes of Alarm Action	Cancellation of Alarm		
Alaini Type	Control Method	Light	Character Display	Alam Output	the time of Alarm Action		Cancellation of Alaim		
Burnt-out Fuse		SYS	/S E01			Burnt-out Fuse			
Frequency failure		SYS	E02			Either of the following: The frequency of control power supply is 40Hz and less or 70Hz and more.	The alarm is cancelled wher control power is turned on		
Stop of a Fan	spo	SYS	E03	ina		A cooling fan is stopped.			
Current failure	Execution of All Methods	SYS		alarm terminal	Suspension of Operation	Output current is 120% or more of the rated current value.	or if the operation mode is changed.		
Trouble of an Element	n of All	SYS	E05			10% or more output when an output signal is 0%.			
Voltage failure	xecutic	SYS	E06	allocated			Either of the following: Voltage is 120% and more of the set voltage or 70% and less of the calculated output value.		
Abnormal Internal Temperature	Ш	SYS E11		the		The internal temperature is 90°C or over.	The alarm is automatically cancelled when the temperature goes down to 60°C or less.		
Snapping of a Heater Wire		H.B cceen		Output from	Operation is continued even after an alarm output	In the case of phase control: Output voltage is 15V or more. In the case of zero-cross switching cycle operation control: The resistance value of a heater is above the set value when output is 10% or more.	The alarm is cancelled when control power is turned on or if the operation mode is changed.		
Current Limit	Phase Control when feedback is used	O.C	Normal		The higher limit value of output current is clipped to the set value.	The current level gets to the set value.	The alarm is turned on or off		
Current Alarm	Phase Control when		.0 2		Operation is continued even after an alarm output	Above the set value	at the set point.		

#### Function and characteristics

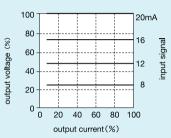
#### Control Method

#### **♦**Phase Control

- Voltage Feedback
- Non-feedback

This function corresponds to load (iron, chromium, nichrome, etc) whose temperature coefficient of electric resistance is small. Feedback type supplies voltage output proportional to control input regardless of power supply voltage changes / load changes.

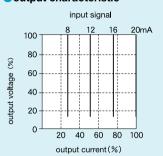
## output characteristic



#### Current Feedback

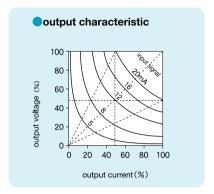
This function corresponds to load (platinum, molybdenum, tungsten, etc) whose temperature coefficient of electric resistance goes up to  $6\!\sim\!12$  times in the normal temperature. It supplies current proportional to control input regardless of power supply voltage changes/load changes.

#### output characteristic



#### Electric Power Feedback

In the case that load is silundum (sic) luminous body, secular changes of resistance/electric resistance occurs due to generation of heat. This function supplies electricity output proportional to control input regardless of load resistance value. Output characteristic is that a curve connected between a point of output voltage 100% x output current 50% and a point of output voltage 50% x output current 100% is equivalent to 50% of output. So set output current capacity of this body to double the load capacity.



#### **◆**Zero-cross Switching Cycle Operation Control

This function enables THYRISTOR to do switching at around voltage 0 and to make less noise. The function makes THYRISTOR environment-friendly.

#### ◆Phase Control + Zero-cross Switching Cycle Operation Control

This function combines merits of the two control methods. Phase control restrains initial current at the time of starting. When output current becomes stable, the control method changes to ZC control. In this way noise becomes less.

#### The Other Functions

**♦Power-on Wait** 

This function control timing of control signals and the body at the time of starting

**♦Soft-start** 

♦Slow-up

These functions restrain a sudden output change to the load when control input is drastically changed, and control the subsequent output to a natural flow

**♦Slow-down** 

◆Higher limiter at the time of starting

◆Time limiter at the time of starting

These functions control the time or output value not to be over the ones that are set at the time of starting

◆Current limiter

This function clip current to the set value when feedback function is used.

♦Current alarm

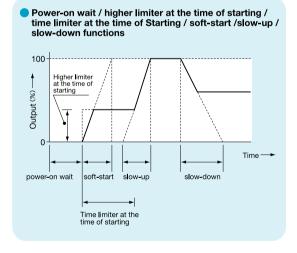
This function is used when feedback function is not used, and keep the operation running even at the time of alarm output

4 D I

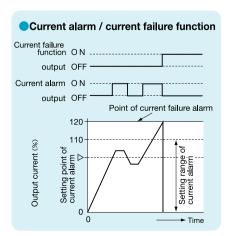
2 points This function is used to change settings from the outside

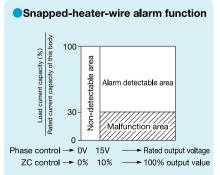
◆Alarm of snapped heater wires

Refer to Table of Alarm Function

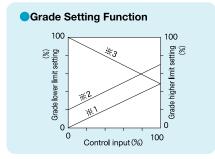


# Point of current failure alarm Japan Jones Jo





When this function is used, set the disparity to be small between the load capacity and the rated capacity of this body



- \*1 Output characteristic when the grade lower limit is set to 0% (output value at the time of input 0%) and the grade higher limit is set to 50% (output value at the time of input 100%)
- \*2 Output characteristic when the grade lower limit is set to 20% and the grade higher limit is set to 70%
- \*3 Output characteristic when the grade lower limit is set to 100% and the grade higher limit is set to 50%

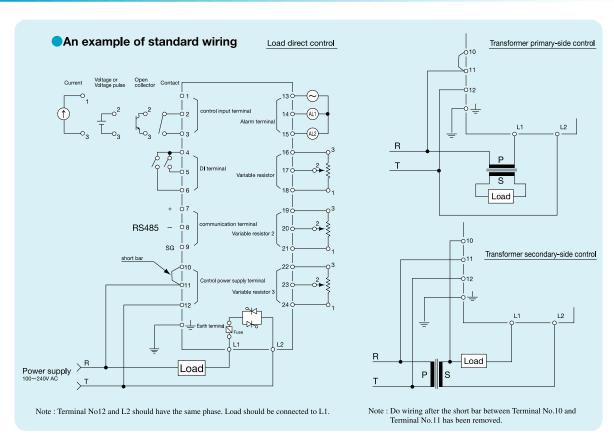
## Ambient Temperature Characteristic

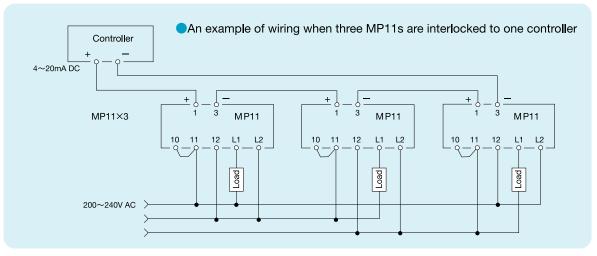
#### Internal Calorific Value

Current-carrying capacity	Element	Fuse	
1~10A	12W	1.8W	
20A	26W	3.1W	
30A	42W	3.7W	
50A	63W	6 <b>.</b> 5W	
70A	86W	11.0W	
100A	132W	14 <b>.</b> 0W	
150A	198W	34 <b>.</b> 0W	
200A	250W	45 <b>.</b> 0W	
300A	381W	50 <b>.</b> 0W	

Internal calorific value of MP11 is shown above. Follow the set-up space and refer to the use environment condition. The set-up site needs to be ventilated and the radiated heat needs to be relieved.

#### Wiring Examples





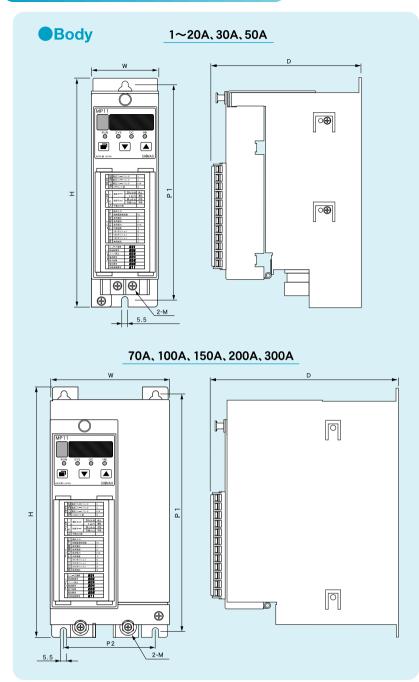
### ■Order Code Table

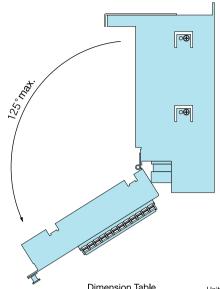
Item	Code	Specification						
		Control Method		Feedback function is used. Phase Control (constant voltage, constant current, constant power, voltage square)  Feedback function is not used. Phase Control (angle, voltage square)  Zero-cross switching cycle operation control Phase Control (angle, voltage square) + Zero-cross switching cycle operation control				
1. Series	MP11—	Input	$4\sim$ 20mA DC Input impedance approx. $165\Omega$ $0\sim$ 20mA DC Input impedance approx. $165\Omega$ $1\sim$ 5V DC Input impedance approx. $15k\Omega$ $0\sim$ 5V DC Input impedance approx. $15k\Omega$ No-voltage contact or open collector 5V 1mA DC Voltage pulse (SSR drive) 12V 1mA DC					
	001~ 010			1A∼10A Custom-made calibration in every 1A				
		020		20A				
		030		30A				
		050		50A				
2. Current-c	carrying apacity	070		70A				
	apaony	100		100A				
		150		150A				
		200		200A				
		300		300A				
			0					
				Used for 1∼10A				
				Used for 20A				
				Us	sed for 30A			
				Used for 50A				
3. Immedia	ately-cut Fus	е	1	Us	sed for 70A			
				Used for 100A				
				Used for 150A				
			Used for 200A					
				Us	sed for 300A			
4, Communication				N Without				
4. Commu	ilication			R	RS485			
5 Chasial	5. Special Mention			0	Without			
5. Special				9	With			

#### Parts Code Table

Item Code		Specification
Item	0000	opeoined ion
	250GH-20S	Responding to Body 1∼10A(20A)
	250GH-32S	Responding to Body 20A (32A)
	250GH-40S	Responding to Body 30A (40A)
	250GH-63S	Responding to Body 50A (63A)
Immediately-cut Fuse	250GH-100S	Responding to Body 70A (100A)
	250GH-125S	Responding to Body 100A (125A)
	250GH-250S	Responding to Body 150A (250A)
	250GH-315S	Responding to Body 200A (315A)
	250GH-450S	Responding to Body 300A (450A)
A Set of Variable Resistor ATT-03 Variable Resist		Variable Resistor+Scale+Knob

#### Drawings of External Dimension

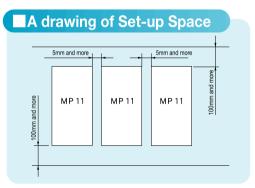


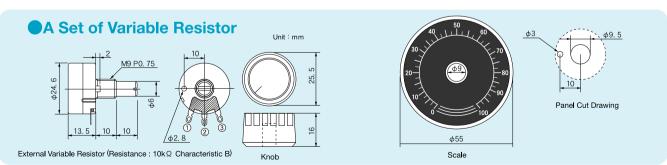


	Dimension Table								
Current-carrying Capacity	W	Н	D	P1	М	Weight (kg)			
1-20A	60	204	133	192	M 4	1.2			
30A	60	204	133	192	M 4	1.4			
50A	70	220	166	208	М5	2.2			

Current-carrying Capacity	W	Н	D	P1	P2	М	Weight (kg)
70A	105	220	166	208	81	М6	2.9
100A	121	240	195	228	97	М6	3.4
150A	121	240	195	228	97	M10	3.7
200A	121	240	195	228	97	M10	3.7
300A	134	273	247	261	110	M12	6.2

Note: Bolt with s hexagonal hold for M10 and M12





The contents of this instruction are subject to change without notice.

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